Warsaw, 1.11.2021

Modelling and Control of Manipulators

Homework 1

Derive the kinematic model of the ABB IRb-7600 manipulator, i.e. solve the direct and inverse kinematic problem for that manipulator.

Deadline for submission of the homework is the 3rd of January, 2022 at noon (12:00). The homework should be submitted to Mr. Maksym Figat.